Leading mech team:

ROS (control robot gripper, also with an xbox controller), Linux, sensors (get results/data from touching it, capacitive sensors) & motors (for the gripper, how to control actuators with ROS, simulating using V-REP, see what weight motors can support), autoCad (building the prototype for the gripper)

Everyone should be learning Python 3, reviewing C and C++ (coding train)

Others will be learning OpenCV and Tensorflow

Try to have everything be operated with ROS nodes

Erin working on AutoCAD robotic arm gripper

Let Peter know in Robotic Arm group, ask if he would be interested in sponsering.

Give info to Anthira

Talk to Daniel and see if he's interested in joining to work on robotic arm